<https://www.section.io/engineering-education/dbscan-clustering-in-python/>

DBSCAN algorithm group points based on distance measurement, usually the Euclidean distance and the minimum number of points. An essential property of this algorithm is that it helps us track down the outliers as the points in low-density regions; hence it is not sensitive to outliers as is the case of K-Means clustering.

DBSCAN algorithm works with two parameters.

These parameters are:

1. **Epsilon (Eps):** This is the least distance required for two points to be termed as a neighbor. This distance is known as Epsilon (Eps). Thus we consider Eps as a threshold for considering two points as neighbors, i.e., if the distance between two points is utmost Eps, then we consider the two points to be neighbors.
2. **MinPoints:** This refers to the minimum number of points needed to construct a cluster. We consider MinPoints as a threshold for considering a cluster as a cluster. A cluster is only recognized if the number of points is greater than or equal to the MinPts.

HOW IT WORKS

* **Step 1:** Initially, the algorithms start by selecting a point (x) randomly from the data set and finding all the neighbor points within *Eps* from it. If the number of *Eps-neighbours* is greater than or equal to **MinPoints**, we consider x a core point. Then, with its *Eps-neighbours*, x forms the first cluster.

After creating the first cluster, we examine all its member points and find their respective *Eps -neighbors*. If a member has at least *MinPoints* *Eps-neighbours*, we expand the initial cluster by adding those *Eps-neighbours* to the cluster. This continues until there are no more points to add to this cluster.

* **Step 2:** For any other core point not assigned to cluster, create a new cluster.
* **Step 3:** To the core point cluster, find and assign all points that are recursively connected to it.
* **Step 4:** Iterate through all unattended points in the dataset and assign them to the nearest cluster at *Eps* distance from themselves. If a point does not fit any available clusters, locate it as a noise point.

Types of data points in a DBSCAN clustering

After the DBSCAN clustering is complete, we end up with three types of data points as follows:

1. **Core:** This is a point from which the two parameters above are fully defined, i.e., a point with at least *Minpoints* within the *Eps* distance from itself.
2. **Border:** This is any data point that is not a core point, but it has at least one *Core point* within *Eps* distance from itself.
3. **Noise:** This is a point with less than *Minpoints* within distance *Eps* from itself. Thus, it’s not a *Core* or a *Border*.

import numpy as np

import matplotlib.pyplot as plt

import pandas as pd

data = pd.read\_csv("Mall\_Customers.csv")

data.head()

#verifique si hay nulos

data.isnull().any().any()

Si no tiene ningun nullo dara output false, si tiene nulo lo elimina

| **CustomerID** | **Genre** | **Age** | **Annual Income (k$)** | **Spending Score (1-100)** |
| --- | --- | --- | --- | --- |
| **0** | 1 | Male | 19 | 15 | 39 |
| **1** | 2 | Male | 21 | 15 | 81 |
| **2** | 3 | Female | 20 | 16 | 6 |
| **3** | 4 | Female | 23 | 16 | 77 |
| **4** | 5 | Female | 31 | 17 | 40 |

x = data.loc[:, ['Annual Income (k$)','Spending Score (1-100)']].values

print(x.shape)

Output

(200,2)

#Compute data proximity from each other using Nearest Neighbours

from sklearn.neighbors import NearestNeighbors # importing the library

neighb = NearestNeighbors(n\_neighbors=2) # creating an object of the NearestNeighbors class

nbrs=neighb.fit(x) # fitting the data to the object

distances,indices=nbrs.kneighbors(x) # finding the nearest neighbours

# Sort and plot the distances results

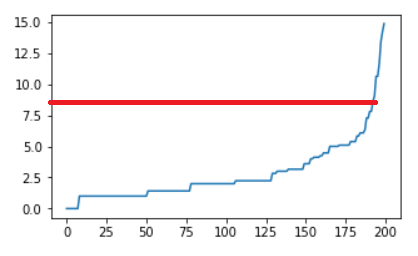
distances = np.sort(distances, axis = 0) # sorting the distances

distances = distances[:, 1] # taking the second column of the sorted distances

plt.rcParams['figure.figsize'] = (5,3) # setting the figure size

plt.plot(distances) # plotting the distances

plt.show() # showing the plot



CON ESTO TENEMOS LOS PARAMETROS

1. MinPoints: We can obtain the minimum number of Points to be used to recognize a cluster, as follows:

* If the dataset has two dimensions, use the min sample per cluster as 4.
* If the data has more than two dimensions, the min sample per cluster should be: Min\_sample(MinPoints) = 2 \* Data dimension

Since our data is two-dimensional, shape= (200,2) we shall use the default value of 4 as our MinPoint parameter.

1. Epsilon (Eps): To calculate the value of *Eps*, we shall calculate the distance between each data point to its closest neighbor using the Nearest Neighbours. After that, we sort them and finally plot them. From the plot, we identify the maximum value at the curvature of the graph. This value is our *Eps*.

From the above plot, we note the maximum curvature of the curve is about eight, and thus we picked our *Eps* as 8.

We now have our two parameters as:

* *MinPoints = 4*
* *Eps = 8*

epsilon = 8

min\_point = 4

from sklearn.cluster import DBSCAN

# cluster the data into five clusters

dbscan = DBSCAN(eps = epsilon, min\_samples = min\_point).fit(x) # fitting the model

labels = dbscan.labels\_ # getting the labels

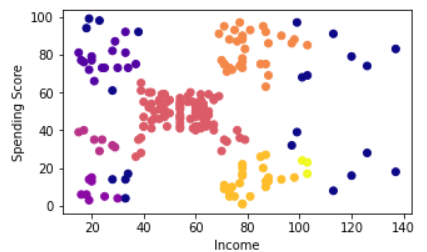
# Plot the clusters

plt.scatter(x[:, 0], x[:,1], c = labels, cmap= "plasma") # plotting the clusters

plt.xlabel("Income") # X-axis label

plt.ylabel("Spending Score") # Y-axis label

plt.show()



SI VARIAMOS EPSILON, A MAYOR EPSILON MENOS DIFERENCIACION

|  |  |  |
| --- | --- | --- |
| 6 | 10 | 12 |
|  |  |  |